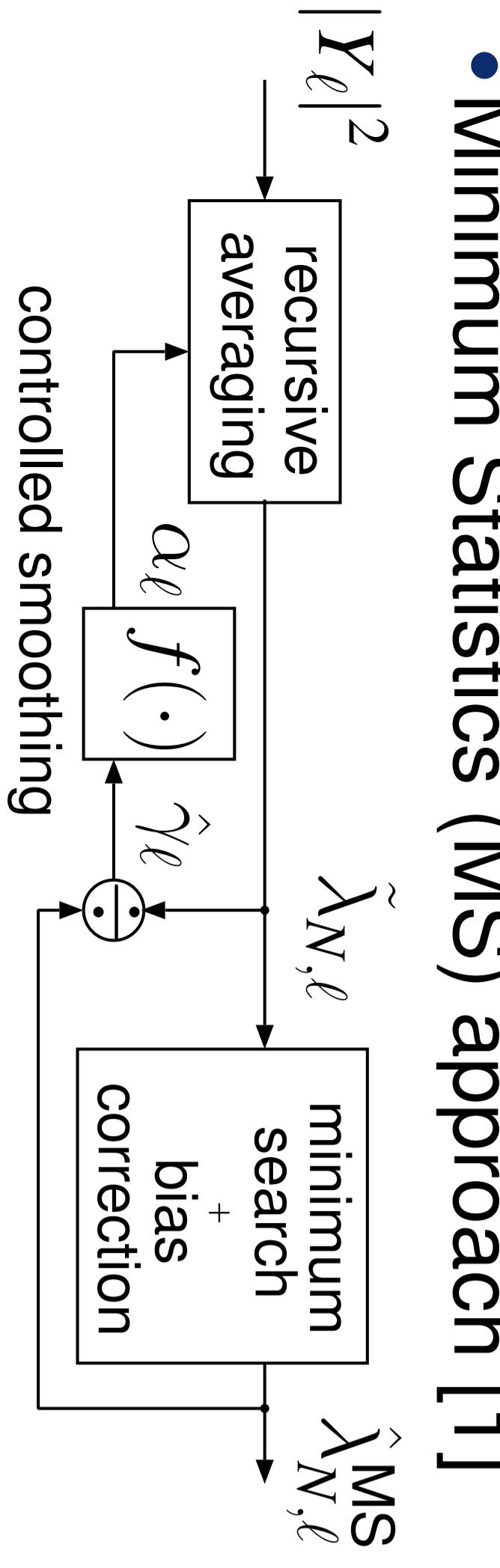


# On Optimal Smoothing in Minimum Statistics Based Noise Tracking

## Introduction

- Noise power spectral density (PSD) estimation is a key component of speech enhancement systems



with the 1. order recursive averaging

$$\hat{\lambda}_{N,\ell} = \alpha_\ell \cdot \hat{\lambda}_{N,\ell-1} + (1 - \alpha_\ell) \cdot |Y_\ell|^2 \quad (1)$$

controlled by smoothed *a posteriori* SNR

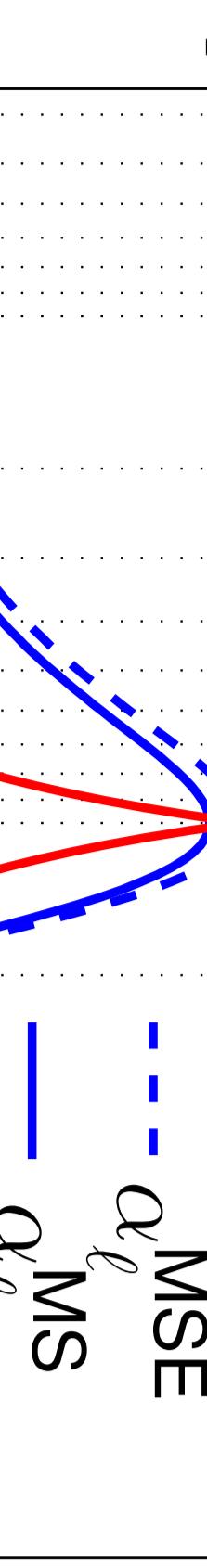
$$\hat{\gamma}_\ell = \frac{\hat{\lambda}_{N,\ell-1}}{\hat{\lambda}_{N,\ell-1}^{\text{MS}}} \quad \text{via} \quad \alpha_\ell = f(\hat{\gamma}_\ell).$$

- We propose a new control function  $f(\cdot)$

## Compare of control functions

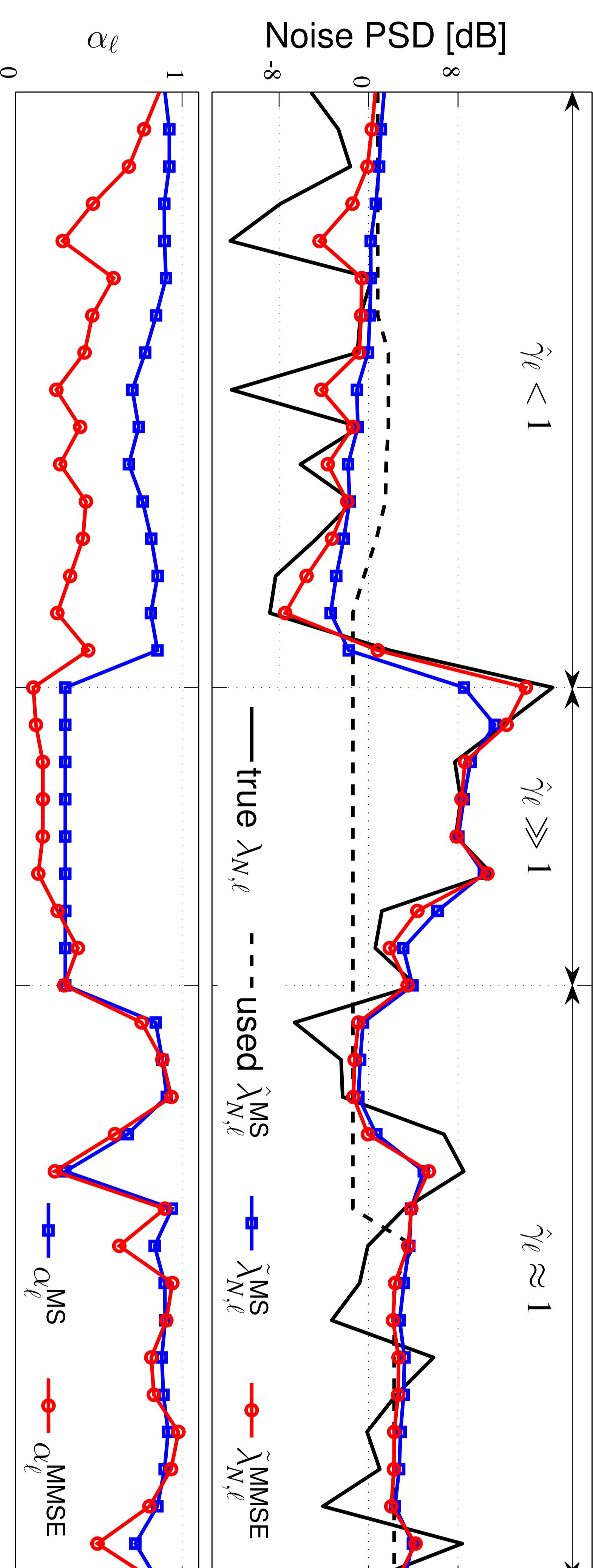
- $\alpha_\ell^{\text{MS}}$  still not able to track  $\lambda_{N,\ell}$  for  $\hat{\gamma}_\ell < 1$

► crucial for the following minimum search



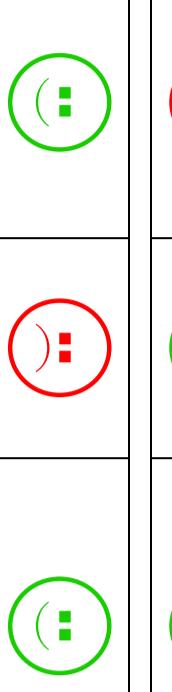
to depend on  $d_\ell$

$$\alpha_\ell^{\text{MMSE}} = \frac{1}{1 + 2 \cdot |\ln \hat{\gamma}_\ell|}$$



Properties of control functions $\alpha_\ell = f(\hat{\gamma}_\ell)$	
$\hat{\gamma}_\ell < 1$	- tracking ability
$\approx 1$	- deadlock
$\gg 1$	- estimator variance

extra parameters



## MS control function [1]

## Proposed control function

- Treat  $\lambda_{N,\ell}$  as a random variable

$$p_{\lambda_{N,\ell}}(x; \nu_\ell, \tau_\ell^2) = \text{Scaled-Inv-}\chi^2(\nu_\ell, \tau_\ell^2)$$

- Update of hyperparameter  $\tau_\ell^2$  in speech absence for MMSE point estimate

$$\hat{\lambda}_{N,\ell}^{\text{MMSE}} = E[\lambda_N | |Y_\ell|^2] = \frac{\nu_\ell}{\nu_\ell - 2} \cdot \tau_\ell^2$$

gives (1) with the smoothing parameter

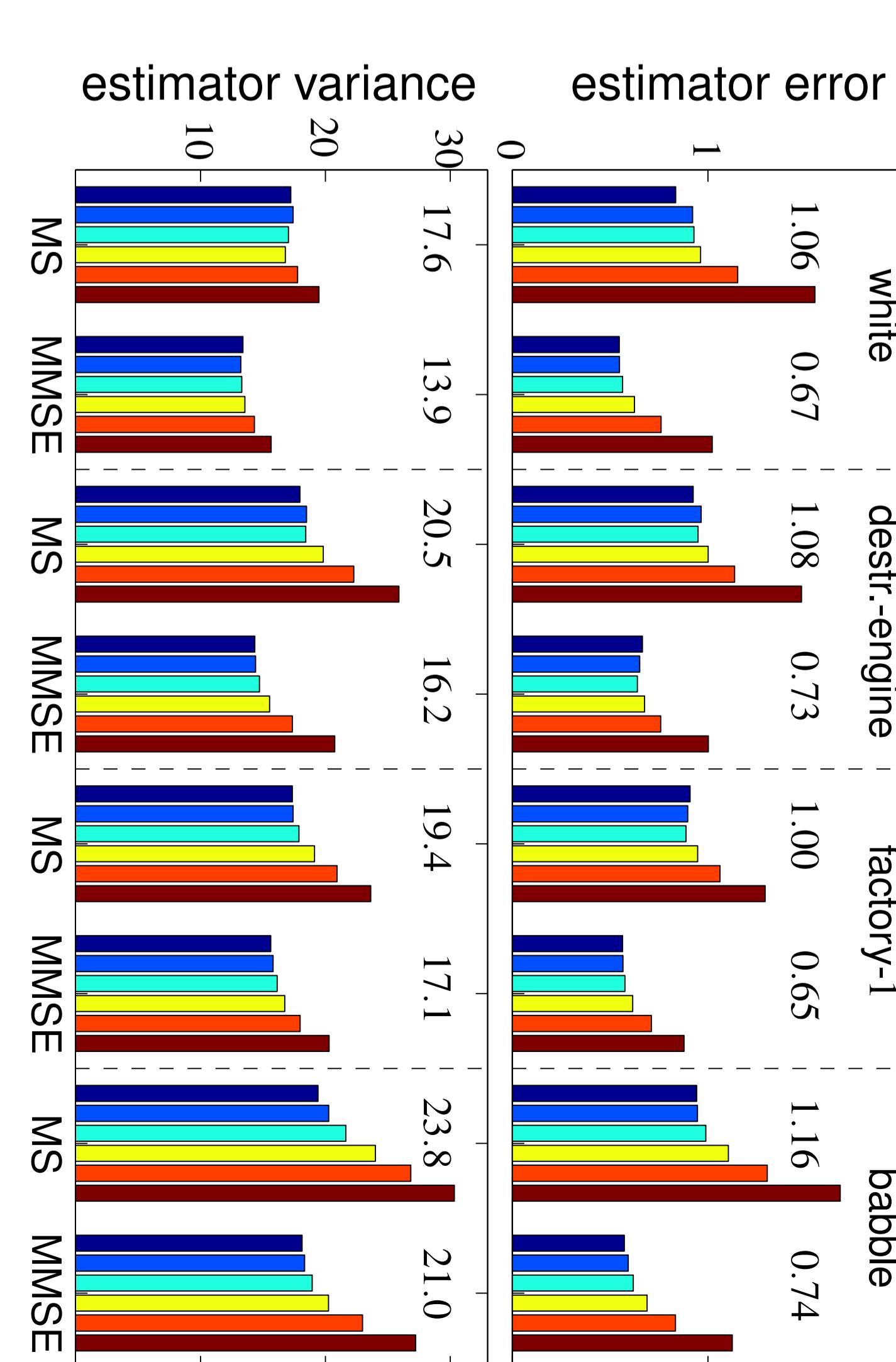
$$\alpha_\ell^{\text{MMSE}} = 1 - \frac{2}{\nu_{\ell-1}} \quad \text{for} \quad \nu_{\ell-1} > 2$$

- Let  $d_\ell = |\ln(\hat{\gamma}_\ell)|$  be a measure of the degree of nonstationarity.

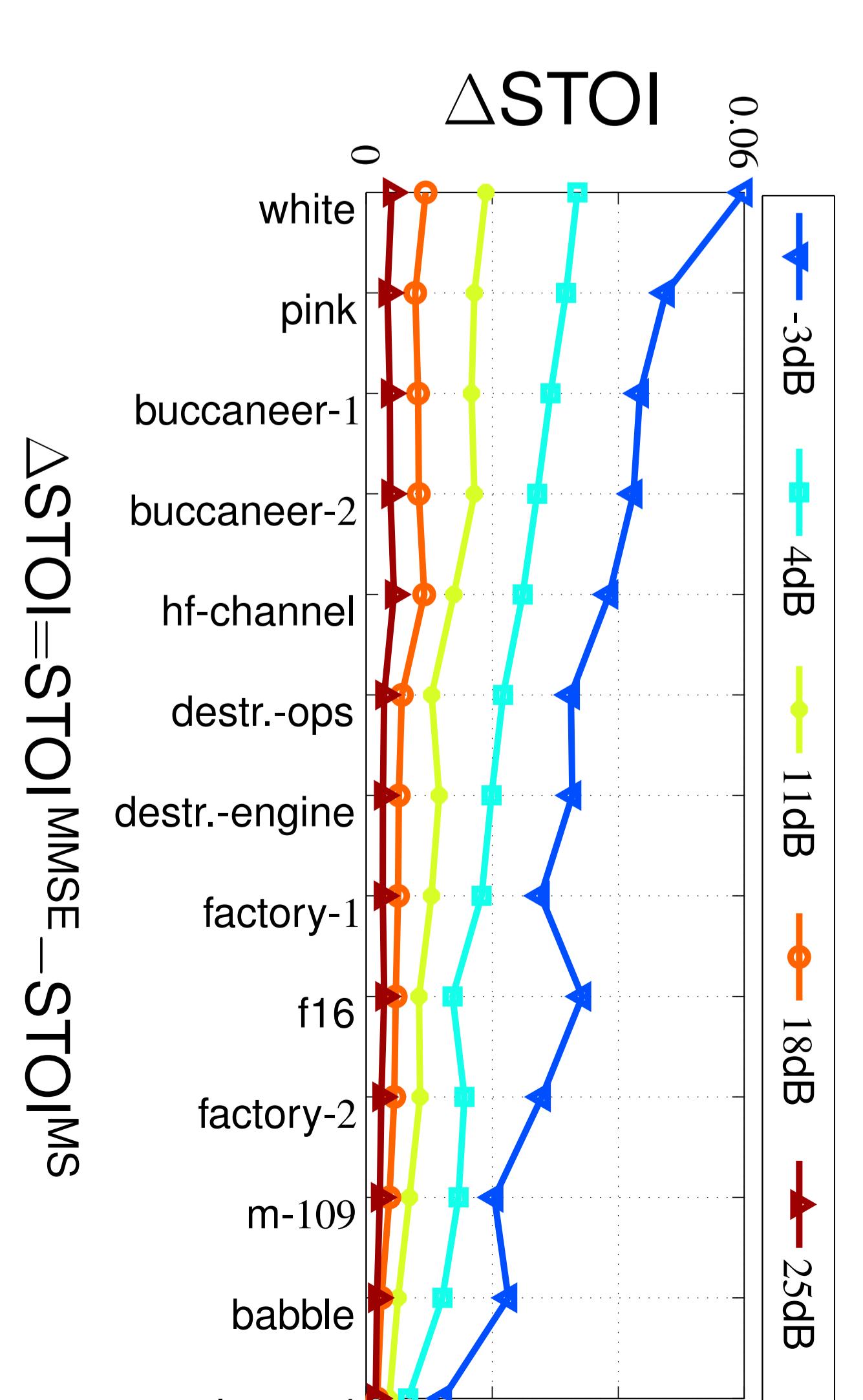
Adjust smoothing parameter  $\alpha_\ell^{\text{MMSE}}$  via

$$\nu_{\ell-1} = 2 + \frac{1}{d_\ell}$$

- Small improvement of speech quality



Noise tracking performance



## Conclusions

- We proposed the MMSE smoothing controlled by a degree of nonstationarity measure for the MS approach [1]
- Improved noise tracking and speech enhancement performance